



Sample Code for Arduino

```
/******Demo for MQ-2 Gas Sensor Module
V1.0*****
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3.0)
Note: This piece of source code is supposed to be used as a demonstration
ONLY. More
sophisticated calibration is required for industrial field application.

*****/
*****/
/******Hardware Related
Macros*****/
#define MQ_PIN (0) //define which analog input channel you are going to use
#define RL_VALUE (5) //define the load resistance on the board, in kilo
ohms
#define RO_CLEAN_AIR_FACTOR (9.83) //RO_CLEAR_AIR_FACTOR=(Sensor resistance
in clean air)/RO,
//which is derived from the chart in datasheet
/******Software Related
Macros*****/
#define CALIBARAION_SAMPLE_TIMES (50) //define how many samples you are
going to take in the calibration phase
#define CALIBRATION_SAMPLE_INTERVAL (500) //define the time interal(in
milisecond) between each samples in the
//cablibration phase
#define READ_SAMPLE_INTERVAL (50) //define how many samples you are going
to take in normal operation
#define READ_SAMPLE_TIMES (5) //define the time interal(in milisecond)
between each samples in
//normal operation
/******Application Related
Macros*****/
#define GAS_LPG (0)
#define GAS_CO (1)
#define GAS_SMOKE (2)
/******Globals*****
*****/
float LPGCurve[3] = {2.3,0.21,-0.47}; //two points are taken from the
curve.
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//with these two points, a line is formed which is "approximately
equivalent"
//to the original curve.
//data format:{ x, y, slope}; point1: (lg200, 0.21), point2: (lg10000, -
0.59)
float COCurve[3] = {2.3,0.72,-0.34}; //two points are taken from the curve.
//with these two points, a line is formed which is "approximately
equivalent"
//to the original curve.
//data format:{ x, y, slope}; point1: (lg200, 0.72), point2: (lg10000,
0.15)
float SmokeCurve[3] = {2.3,0.53,-0.44}; //two points are taken from the
curve.
//with these two points, a line is formed which is "approximately
equivalent"
//to the original curve.
//data format:{ x, y, slope}; point1: (lg200, 0.53), point2: (lg10000, -
0.22)
float Ro = 10; //Ro is initialized to 10 kilo ohms
void setup()
{
Serial.begin(9600); //UART setup, baudrate = 9600bps
Serial.print("Calibrating...\n");
Ro = MQCalibration(MQ_PIN); //Calibrating the sensor. Please make sure the
sensor is in clean air
//when you perform the calibration
Serial.print("Calibration is done...\n");
Serial.print("Ro=");
Serial.print(Ro);
Serial.print("kohm");
Serial.print("\n");
}
void loop()
{
Serial.print("LPG:");
Serial.print(MQGetGasPercentage(MQRead(MQ_PIN)/Ro,GAS_LPG) );
Serial.print(" ppm" );
Serial.print(" ");
Serial.print("CO:");
Serial.print(MQGetGasPercentage(MQRead(MQ_PIN)/Ro,GAS_CO) );
Serial.print(" ppm" );
Serial.print(" ");
Serial.print("SMOKE:");
Serial.print(MQGetGasPercentage(MQRead(MQ_PIN)/Ro,GAS_SMOKE) );
Serial.print(" ppm" );
Serial.print("\n");
delay(200);
}
/***** MQResistanceCalculation
*****
Input: raw_adc - raw value read from adc, which represents the voltage
Output: the calculated sensor resistance
Remarks: The sensor and the load resistor forms a voltage divider. Given
the voltage
across the load resistor and its resistance, the resistance of the sensor
could be derived.
*****/
float MQResistanceCalculation(int raw_adc)
{
return ( ((float)RL_VALUE*(1023-raw_adc)/raw_adc));
}

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/***** MQCalibration
*****
Input: mq_pin - analog channel
Output: Ro of the sensor
Remarks: This function assumes that the sensor is in clean air. It use
MQResistanceCalculation to calculates the sensor resistance in clean air
and then divides it with RO_CLEAN_AIR_FACTOR. RO_CLEAN_AIR_FACTOR is about
10, which differs slightly between different sensors.
*****/
float MQCalibration(int mq_pin)
{
int i;
float val=0;

for (i=0;i<CALIBARAION_SAMPLE_TIMES;i++) { //take multiple samples
val += MQResistanceCalculation(analogRead(mq_pin));
delay(CALIBRATION_SAMPLE_INTERVAL);
}
val = val/CALIBARAION_SAMPLE_TIMES; //calculate the average value

val = val/RO_CLEAN_AIR_FACTOR; //divided by RO_CLEAN_AIR_FACTOR yields the
Ro
//according to the chart in the datasheet

return val;
}
/***** MQRead
*****
Input: mq_pin - analog channel
Output: Rs of the sensor
Remarks: This function use MQResistanceCalculation to caculate the sensor
resistenc (Rs).
The Rs changes as the sensor is in the different consentration of the
target
gas. The sample times and the time interval between samples could be
configured
by changing the definition of the macros.
*****/
float MQRead(int mq_pin)
{
int i;
float rs=0;
for (i=0;i<READ_SAMPLE_TIMES;i++) {
rs += MQResistanceCalculation(analogRead(mq_pin));
delay(READ_SAMPLE_INTERVAL);
}

rs = rs/READ_SAMPLE_TIMES;

return rs;
}
/***** MQGetGasPercentage
*****
Input: rs_ro_ratio - Rs divided by Ro
gas_id - target gas type
Output: ppm of the target gas
Remarks: This function passes different curves to the MQGetPercentage
function which
calculates the ppm (parts per million) of the target gas.
*****/

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int MQGetGasPercentage(float rs_ro_ratio, int gas_id)
{
if ( gas_id == GAS_LPG ) {
return MQGetPercentage(rs_ro_ratio,LPGCurve);
} else if ( gas_id == GAS_CO ) {
return MQGetPercentage(rs_ro_ratio,COCurve);
} else if ( gas_id == GAS_SMOKE ) {
return MQGetPercentage(rs_ro_ratio,SmokeCurve);
}
}

return 0;
}
/***** MQGetPercentage
*****/
Input: rs_ro_ratio - Rs divided by Ro
pcurve - pointer to the curve of the target gas
Output: ppm of the target gas
Remarks: By using the slope and a point of the line. The x(logarithmic
value of ppm)
of the line could be derived if y(rs_ro_ratio) is provided. As it is a
logarithmic coordinate, power of 10 is used to convert the result to non-
logarithmic
value.
*****/
int MQGetPercentage(float rs_ro_ratio, float *pcurve)
{
return (pow(10,( (log(rs_ro_ratio-pcurve[1])/pcurve[2]) + pcurve[0])));
}

```

Demo Output

